$\left\{ \operatorname{Csc} 80030 \mid \operatorname{Lecture} 10 \right\}$

PROBABILISTIC ANALYSIS & RANDOMIZED ALGORITHMS

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part 0

- ► HOMEWORK: HW5 due May 6
- ► PRESENTATIONS:
 - May 6 Michael (balls and bins), Ben (sublinear-time algorithm), Peter (hiring problem)
 - May 13 Valia (balls and bins), Justin
 - Homework problem requirement
- ► TODAY: expander graphs

PART 1 expander graphs

Expander graphs

- 1. "sparse"
 - constant degree \implies linear # of edges
- 2. "well-connected"
 - (K, A) vertex expansion: for all sets S of ≤ K vertices, the neighborhood N(S) has size ≥ A · |S|.



• would like $K = \Omega(N)$ and $A \sim D$.

Expander graphs

- 1. "sparse"
 - constant degree \implies linear # of edges
- 2. "well-connected"
 - (K, A) vertex expansion: for all sets S of ≤ K vertices, the neighborhood N(S) has size ≥ A · |S|.
 - edge expansion: # edges leaving S is large (i.e. no small cuts)
 - ▶ random walks: converge quickly to uniform, i.e., 2nd eigenvalue is small

QUESTION.

- ► Do good expanders exist?
- Specifically, (K, A) vertex expanders with $K = \Omega(N), A = 1 + \Omega(1)$?

Random graphs are good expanders

- ► THEOREM. For all D ≥ 3, there is a constant α > 0 s.t. a random D-regular graph on N vertices is an (αN, D − 1.01) vertex expander with prob. ≥ 1/2.
 - ► D ≥ 3 is necessary every graph of degree 2 is a poor expander (being a union of cycles and chains).
 - will only prove a simpler result for bipartite expanders.

Random graphs are good expanders

- ► THEOREM. For all D ≥ 3, there is a constant α > 0 s.t. a random D-regular graph on N vertices is an (αN, D − 1.01) vertex expander with prob. ≥ 1/2.
- ▶ DEFINITION. A bipartite graph is a (*K*, *A*) vertex expander if for all sets of $\leq K$ left vertices, the neighborhood *N*(*S*) has size $\geq A \cdot |S|$.



▶ THEOREM. For all $D \ge 3$, there is a constant $\alpha > 0$ s.t. a random

D-left-regular (N, N)-bipartite graph is an $(\alpha N, D-2)$ vertex expander

Random bipartite expanders

- ► THEOREM. For all D ≥ 3, there is a constant α > 0 s.t. a random D-left-regular (N, N)-bipartite graph is an (αN, D − 2) vertex expander with prob. ≥ 1/2.
- ► STEP 1. Fix *S* of size $K \le \alpha N$. Show that $\Pr[|N(S)| \le (D-2) \cdot K] \le {\binom{KD}{2K}} {\binom{KD}{N}}^{2K}$
- ▶ STEP 2. Take a union bound over *S* and *K*.

$$\sum_{K=1}^{\alpha N} {N \choose K} {KD \choose 2K} \left(\frac{KD}{N}\right)^{2K} \leq \sum_{K=1}^{\alpha N} \left(\frac{Ne}{K}\right)^{K} \left(\frac{KDe}{2K}\right)^{2K} \left(\frac{KD}{N}\right)^{2K} = \sum_{K=1}^{\alpha N} \left(\frac{e^{3}D^{4}K}{4N}\right)^{K}$$
$$\leq \sum_{K=1}^{\alpha N} \left(\frac{1}{4}\right)^{K} < \frac{1}{2} \quad \text{setting } \alpha = \frac{1}{e^{3}D^{4}}.$$

Applications

- construction of fault-tolerant networks
- sorting in $O(\log n)$ time in parallel
- ► derandomization (e.g. of UNDIRECTED S-T CONNECTIVITY)
- error-correcting codes
- distributed routing
- data structures
- negative results for integrality gaps for linear programming relaxations and metric embeddings
- ▶ Need *explicit* constructions (i.e. deterministic and efficient)

PART 2 | expansion and eigenvalues

Second eigenvalue

► DEFINITION. For an *n*-vertex regular graph *G* with random-walk matrix *M*, we define

$$\lambda(G) = \max_{\pi \in [0,1]^N} \frac{\|\pi M - u\|}{\|\pi - u\|}$$

- ► INTERPRETATION. If $\lambda(G)$ is small, then random walk on *G* converges quickly to uniform.
 - $||\pi M u|| \le \lambda ||\pi u||$
 - $||\pi M^k u|| \le \lambda^k ||\pi u||$

Second eigenvalue

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$$\lambda(G) = \max_{\pi \in [0,1]^N} \frac{\|\pi M - u\|}{\|\pi - u\|}$$

► CLAIM. Let $1 = \lambda_1, \lambda_2, ..., \lambda_N$ be the eigenvalues of M, with $|\lambda_1| \ge |\lambda_2| \ge \cdots \ge |\lambda_N|$. Then, $\lambda(G) = |\lambda_2|$ ("2nd eigenvalue").

• Write
$$\pi = u + c_2 v_2 + \cdots + c_N v_N$$
.

• Hence, $\pi M = u + c_2 \lambda_2 v_2 + \dots + c_N \lambda_N v_N$.

Now,
$$\|\pi M - u\|^2 = c_2^2 \lambda_2^2 \|v_2\|^2 + \dots + c_N^2 \lambda_N^2 \|v_N\|^2$$

 $\leq \lambda_2^2 (c_2^2 \|v_2\|^2 + \dots + c_N^2 \|v_N\|^2)$
 $= \lambda_2^2 \|\pi - u\|^2$

Expansion and eigenvalues

- ► THEOREM. If *G* is a regular graph with 2nd eigenvalue λ , then *G* is an $(N/2, 2 \lambda)$ vertex expander.
 - smaller λ , better expansion.
 - 2λ is "best possible."
 - In fact, $\forall \alpha \in [0, 1]$, G is an $(\alpha N, 1/((1 \alpha)\lambda^2 + \alpha))$ vertex expander.

Expansion and eigenvalues

- ► THEOREM. If G is a regular graph with 2nd eigenvalue λ , then \forall subsets S of size $\leq \alpha N$, $|N(S)| \geq |S|/(1-\alpha)\lambda^2 + \alpha)$.
- DEFINITIONS. For a prob. distribution π ,
 - The *collision probability* of π is the prob. that two independent samples are equal, i.e., $CP(\pi) = \sum_{x} \pi_x^2$.
 - The support of π is Supp $(\pi) = \{x : \pi_x > 0\}.$
- CLAIMS. For any prob. distribution $\pi \in [0, 1]^N$,
 - $CP(\pi) = ||\pi||^2 = ||\pi u||^2 + 1/N.$
 - $\operatorname{CP}(\pi) \ge 1/\operatorname{Supp}(\pi)$. (since $(\sum_x \pi_x^2) \cdot (\sum_x 1) \ge (\sum_x \pi_x)^2$)
- KEY IDEA. set π to be uniform over S.

- ► THEOREM. If G is a regular graph with 2nd eigenvalue λ , then \forall subsets S of size $\leq \alpha N$, $|N(S)| \geq |S|/(1-\alpha)\lambda^2 + \alpha)$.
 - ► STEP 1. for all π , $\|\pi M u\|^2 \le \lambda^2 \|\pi u\|^2$. 1st claim \implies CP $(\pi M) - \frac{1}{N} \le \lambda^2 (CP(\pi) - \frac{1}{N})$.
 - ► STEP 2. set π to be uniform over S. Then, 2nd claim \implies CP $(\pi M) \ge$ Supp $(\pi M) = 1/|N(S)|$. Also, CP $(\pi) = 1/|S|$.
 - COMBINING, $\frac{1}{|N(S)|} \frac{1}{N} \le \lambda^2 (\frac{1}{|S|} \frac{1}{N})$

- ► THEOREM. Let *G* be an infinite family of *D*-regular multigraphs for a constant *D*. Then, the following two conditions are equivalent:
 - "good" vertex expansion:

 \exists constant $\delta_1 < 1$ s.t. every $G \in \mathcal{G}$ is an $(N/2, 2 - \delta_1)$ vertex expander.

"small" 2nd eigenvalue:

 \exists constant $\delta_2 < 1$ s.t. every $G \in \mathcal{G}$ has 2nd eigenvalue at most δ_2 .

- ▶ NOTE. $(2) \implies (1)$ as before; the other direction is "hard" (omitted).
- The term "expander" typically refers to a family of regular graphs of constant degree satisfying one of the two equivalent conditions.

PART 3 towards explicit constructions

- ► APPROACH. iterative constructions
 - 1. Start with a "constant size" expander H.
 - Repeatedly apply graph operations to get better expanders. increase # nodes, keep degree and 2nd eigenvalue bounded.
- ► DEFINITION. a (N, D, λ) -graph is a *D*-regular graph on *N* vertices with 2nd eigenvalue $\leq \lambda$.

- ► GRAPH SQUARING. If G = (V, E) is a D-regular graph, then G² = (V, E') is a D²-regular graph on the same vertex set, E' comprises pairs of vertices connected by a path of length 2 in G.
- ▶ LEMMA. If G is a (N, D, λ) -graph, then G^2 is a (N, D^2, λ^2) -graph.
 - If *M* is random-walk matrix for *G*, then M^2 is random-walk matrix for G^2 .

THE END next, ...