

Structuring the Computation

1.	Objectives	2
2.	Strong Typing & Type Checking	3
3.	Type Compatibility	4
4.	Type Conversion.....	5
5.	Type and Subtypes.....	6
6.	Generic Types	7
7.	Monomorphic versus Polymorphic	8
8.	The Type Structure of Representative languages.....	9
9.	Implementation Models	9
10.	Implementation of Structured Types	11

1. Objectives

- To control flow among the different constructs in a program.
-
- This is key to understanding the *semantics* of the language
- Type error can be classified into two categories:
 - Application errors
 - Language errors.
- Language errors:
 - Here we only address *language errors*, as opposed to *application errors*
 - Language errors are **programmer errors** in how a language's syntax and semantics are defined.
 - There are two categories
 - Syntactic
 - Semantic
- **Type Safety**: guarantee no type errors
- Another Classification:
 - Static:
 - During compilation
 - It is preferred.

- Not all errors can be detected at compile time, e.g., memory availability and division by zero.
- Dynamic:
 - At run time.
 - Slow down program execution.

2. Strong Typing & Type Checking

- A type system is said to be strong if it guarantees not to generate type errors.
- **Strongly typed languages:** Languages that have strong type systems.
- **Weakly typed languages:** languages that are not strongly typed.
- Coercion rules weakens the value of strong typing
- Static Type System:
 - The type of each expression must be known at compile time.
 - Requirements of a static type system include:
 - Only built-in types can be used
 - All variables are declared with an associate type.
 - All operations are specified by stating the types of the required operands and the type of the results.

- **Statically Typed Languages are Strongly Typed Languages.**

3. Type Compatibility

- A compatible type is one that is either legal for the operator, or is allowed under language rules to be implicitly converted, by compiler-generated code, to a legal type.
- Type compatibility is also called conformance or equivalence.
- There are two type compatibility methods:
 - **Name compatibility** (also called strict compatibility):
 - Two variables can have compatible types only if they are in either the same declaration or in declarations that use the same type name.
 - It is highly restrictive.
 - It is easier to implement.
 - Ada uses name compatibility.
 - **Structure type compatibility:**
 - Two variables have compatible types if their types have identical structures.
 - It is more flexible.
 - It is difficult to implement: compare the whole structure instead of just names.
 - Two types are structurally compatible if:
 1. T1 is name compatible with T2;
or

2. T1 and T2 are defined by applying the same type constructor to structurally compatible corresponding type components.

○ Examples:

1. Two records or structure types compatible if they have same structure but different field names?
2. Two single-dimensioned array types in a Pascal or Ada program are compatible if they have the same element type but have different subscript ranges?
3. C uses structural compatibility except for structures.

4. Type Conversion

- It is needed when the types of an expression are not compatible.
- Some programming languages allow automatic conversions (Also called **coercion**):

What would the following C program output?

```
#include <stdio.h>

main(){

    char c1 = 'a';
    int i = 10;
```

```

        i += c1;
        printf(" The value of i is:%d\n",i);
    }

```

- Formally, the conversion of a type T_1 to another type R_1 is defined as follows:

$\text{func}: T_1 \rightarrow T_2$

For example:

```

    T1 x1;
    T2 x2;

    x2 = func(x1);

```

- How to use `func` to convert from another type T_2 to another type R_2 ?

Requirements: Two new functions t_{21} and r_{12} :

$t_{21}: T_2 \rightarrow T_1$
 $r_{12}: R_1 \rightarrow R_2$

Let x_2 be a variable of type T_2 and y_2 be a variable of type R_2 , then apply t_{21} to x_2 , evaluate `func`, apply r_{12} to the result, and assign it to y_2 :

$y_2 = r_{12} (\text{func}(t_{21}(x_2)));$

5. Type and Subtypes

- A *type* is defined by:
 - A set of values
 - A set of operations

- A *subtype* ST of a basic type T (also called parent type or supertype) can be defined as
 - A subset of the values of T
 - Assume that operations of T are *inherited* by ST
- A language supporting subtypes must provide:
 - A way to define subsets of a given type, and
 - Compatibility rules between a subtype and its supertype
 - Example: Ada subtype

```
SUBTYPE Day_Range IS Integer RANGE 0..31;
SUBTYPE Year_Range IS Integer RANGE 1901..2099;
SUBTYPE natural IS integer range 0..integer'last;
```

```
SUBTYPE natural IS integer RANGE 0..integer'last;
SUBTYPE positive IS integer RANGE 1..integer'last;
```

6. Generic Types

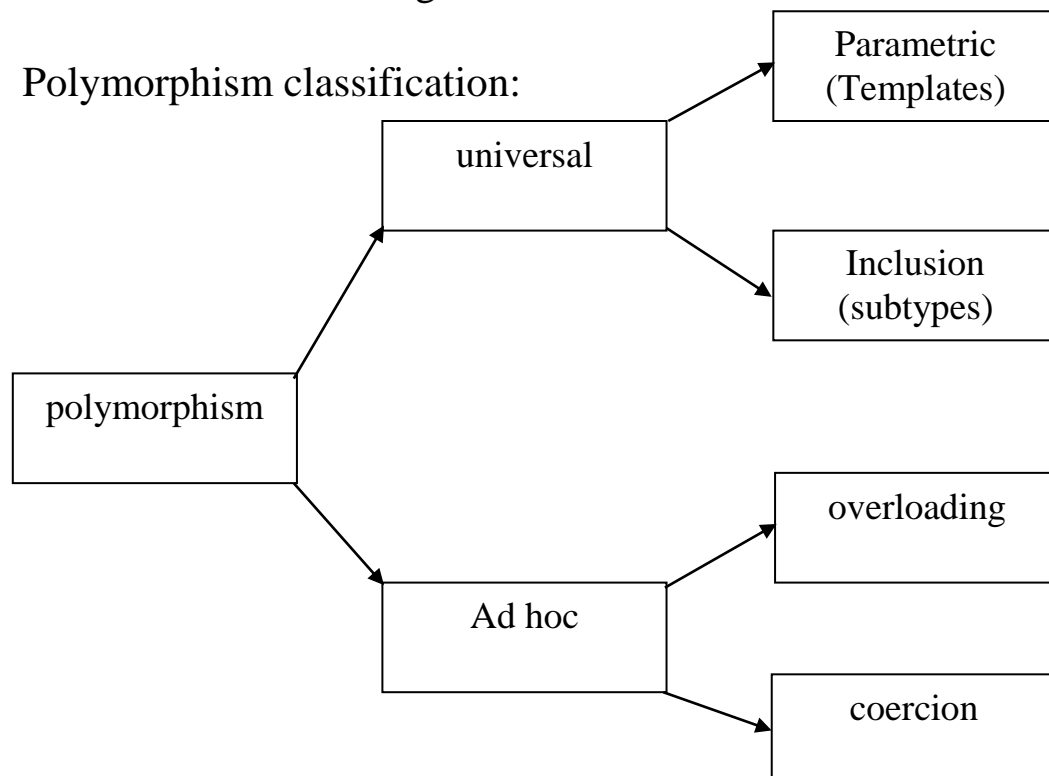
- It allows functions and ADT to have generic types
- How type-checking is done to guarantee type safety?
 - Bind generic types to concrete types at compile-time instantiation.
- Example:

```
push: stack(T)xT → stack(T)
pop: stack(T) → stack(T)xT
length: stack(T) → int
```

7. Monomorphic versus Polymorphic

- Monomorphic: It is a strict type system.
- Polymorphic: It is the case where an object can have more than one type
- Most practical programming languages have some degree of polymorphism.
- Languages deviates form strict monomorphic if they include one of the following:
 - Type equivalence
 - Coercion
 - Subtyping
 - Overloading

- Polymorphism classification:



- **Ad hoc** : functions work on a finite small set of types and may behave differently for each:
 - Overloading
 - Coercion
- **Universal**: work uniformly for an infinite set of types, all of which have common structure
 - Parametric
 - Inclusion

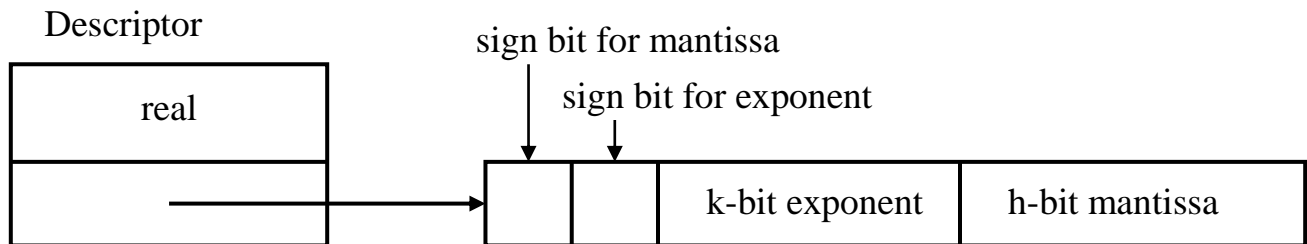
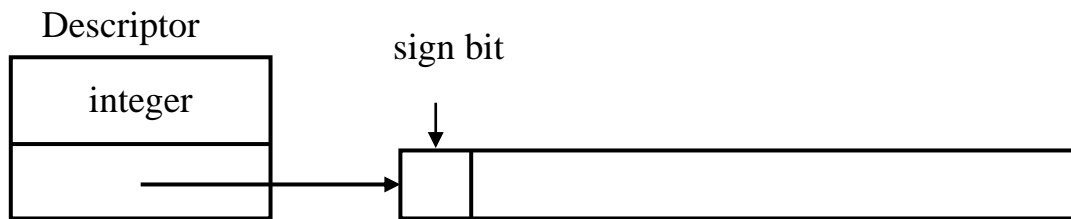
8. The Type Structure of Representative languages

- Java:
 - Computation unit is a class
 - User class construct to create new types
- C++
 - Uses the **class** construct to declare new types
 - Templates
- Ada
 - Subtypes do not constitute new types, so parent-type operations still apply
 - Generic packages

9. Implementation Models

- How to represent data objects inside the machine
- The implementation of each data object requires two elements:

- Descriptor: structures used to store the attributes of the data
 - Data object: memory locations to store the actual values
- Built-in Primitive types:
 - Integers and reals are supported on most computers
 - They may also provide different sized versions of these types
 - Representations:

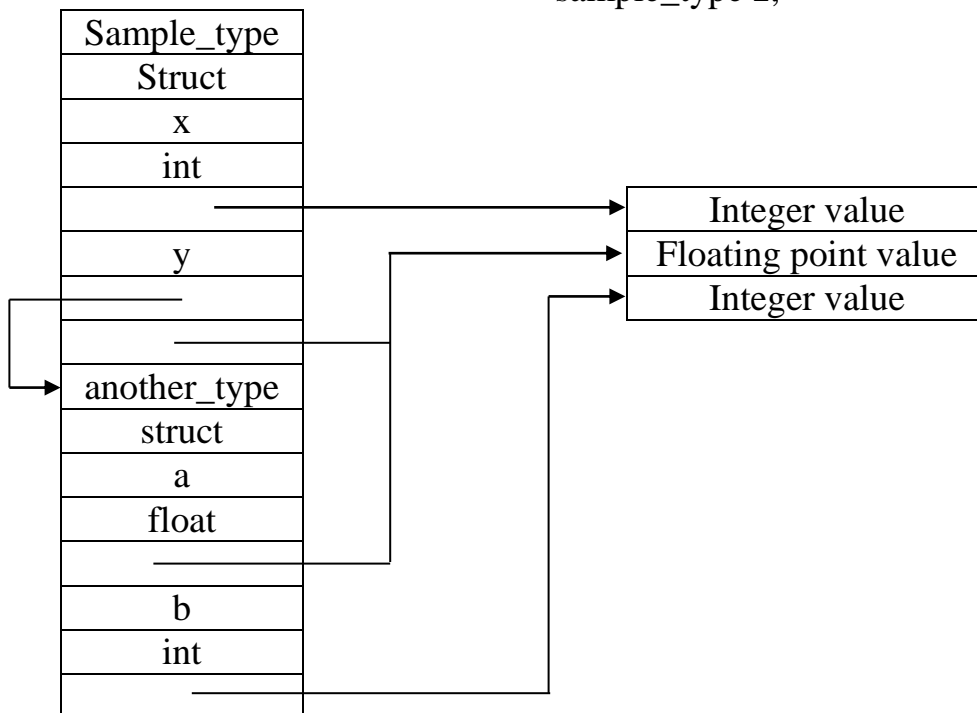


10. Implementation of Structured Types

- Cartesian product:
 - It is a sequential layout of components.
 - The descriptor contains the following:
 - The Cartesian product type name and
 - For each field:
 - Name of the selector
 - Type of the field
 - Reference to the data object
 - Example:

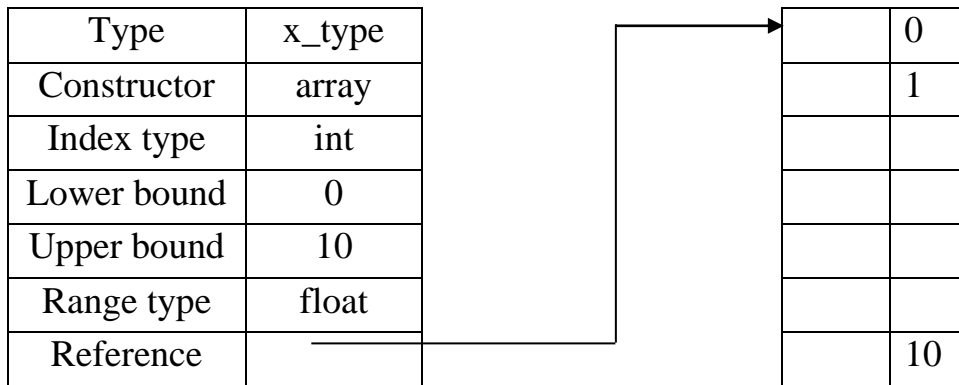
```

type another_type is struct{
    float a;
    int b;
};
type sample_type is struct{
    int x;
    another_type y;
};
sample_type z;
  
```



- Finite Mapping
 - Allocate storage units for each element component.
 - The descriptor contains the following:
 - The mapping type name
 - The name of the domain type
 - Values for the upper and lower bounds.
 - The name of the range type
 - A reference to the first location of the mapping
 - Example:


```
type x_type is float array[0..10];
x_type x;
```

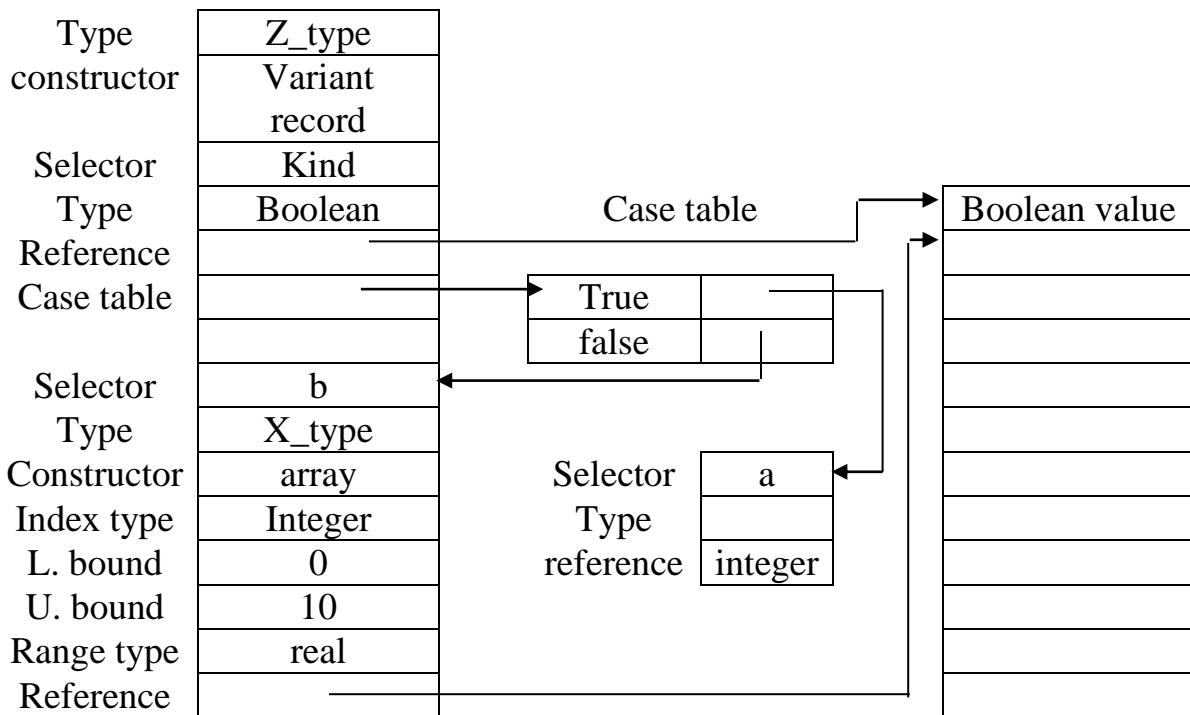


- Union and discriminated union
 - The descriptor of a variable of a union type is the sequence of the descriptors of each component.
 - Example:

```

type x_type = array[0..10] of real;
type z_type = record
    case kind: boolean of
        true: (a:integer);
        false: (b:x_type);
    end;

```



- Powerset
 - Use bit-mapping to represent a set
 - Use AND for Intersection and OR for union
 - Example:

$$S = \{1, 3, 10, 16\}$$

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
0	1	0	1	0	0	0	0	0	0	1	0	0	0	0	0	10	0	0	0